

A short course on

Indeterminate Structures

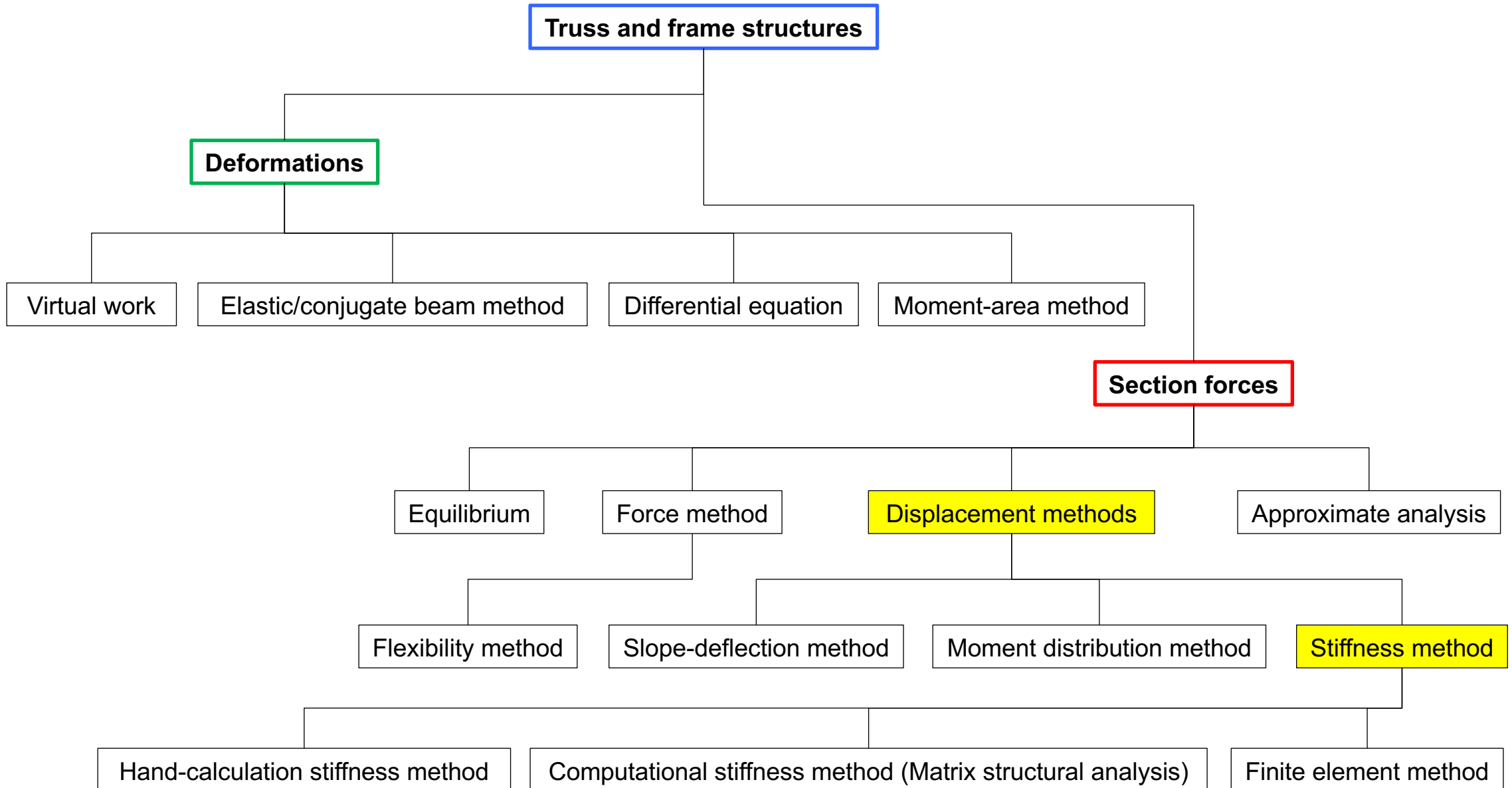
This video:

Stiffness Method

Terje's Toolbox is freely available at terje.civil.ubc.ca

It is created and maintained by Professor Terje Haukaas, Ph.D., P.Eng.,
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Overview of Methods

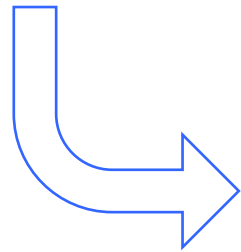


Reference: Slope Deflection Method

1. Identify the **degrees of freedom**, i.e., the unknown displacements and rotations
2. Establish equilibrium equations in terms of end moments
3. Substitute slope-deflection equation for end moments
4. **Solve** for the unknown displacements and rotations
5. Substitute displacements and rotations into **slope-deflection equation** to get end moments
6. Draw **bending moment diagram** between known end moment values

Reference: Slope Deflection Method

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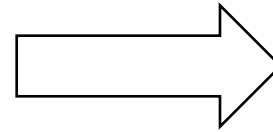
$$\left(\quad \right) \theta_A + \left(\quad \right) \theta_B = \text{loads}$$

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Stiffness Method

$$\begin{pmatrix} \\ \end{pmatrix} \theta_A + \begin{pmatrix} \\ \end{pmatrix} \theta_B = \text{loads}$$

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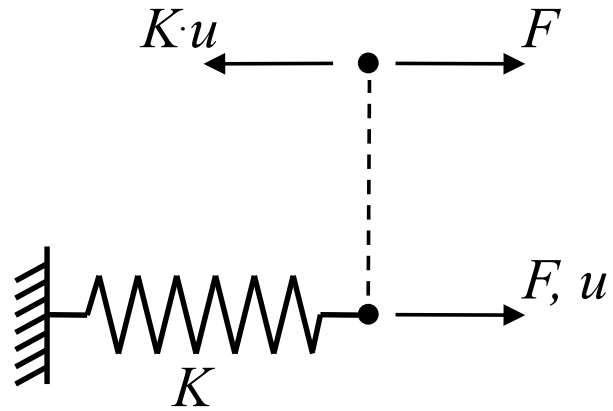


$$\mathbf{Ku} = \mathbf{F}$$

Stiffness Method Procedure

1. Identify the **degrees of freedom**, i.e., the unknown displacements and rotations
2. Establish stiffness matrix, **K**
3. Establish load vector, **F**
4. **Solve** for the unknown displacements and rotations
5. Substitute displacements and rotations into **slope-deflection equation** to get end moments
6. Draw **bending moment diagram** between known end moment values

The Stiffness Concept



Equilibrium: $K u = F$

More Degrees of Freedom

$$K_{11} u_1 + K_{12} u_2 = F_1$$

$$K_{21} u_1 + K_{22} u_2 = F_2$$

$$\mathbf{K} \mathbf{u} = \mathbf{F}$$

$$K_{ij} u_j = F_i$$

K_{ij} = force along DOF number i due to a unit displacement or rotation along DOF number j

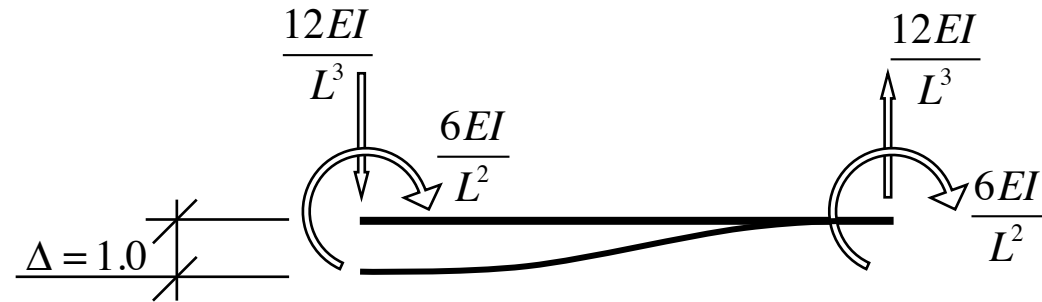
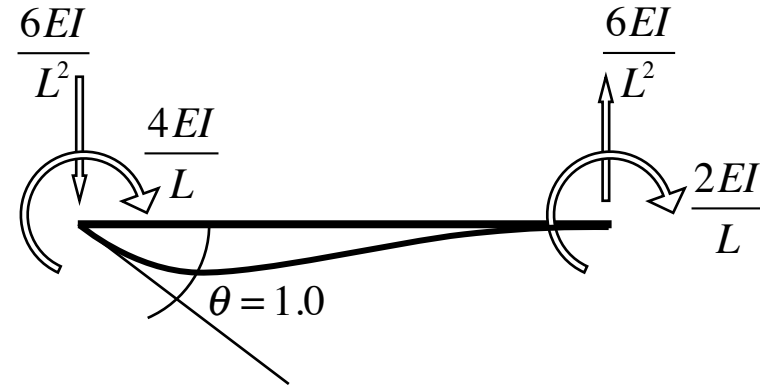
u_j = unknown displacement or rotation along DOF number j

F_i = force along DOF number i due to external loads

Establish \mathbf{K}

1. Sketch the displaced shape of the structure for a unit displacement or rotation along DOF number j , with all other DOFs clamped
2. Determine the force along every DOF to maintain this displaced shape, i.e., K_{ij} , which form column number j of the stiffness matrix
3. Carry out Step 1 and 2 for all DOFs to establish column by column of the stiffness matrix
4. Check that the \mathbf{K} is symmetric with only positive entries on the diagonal

Formula Sheet



Load Vector

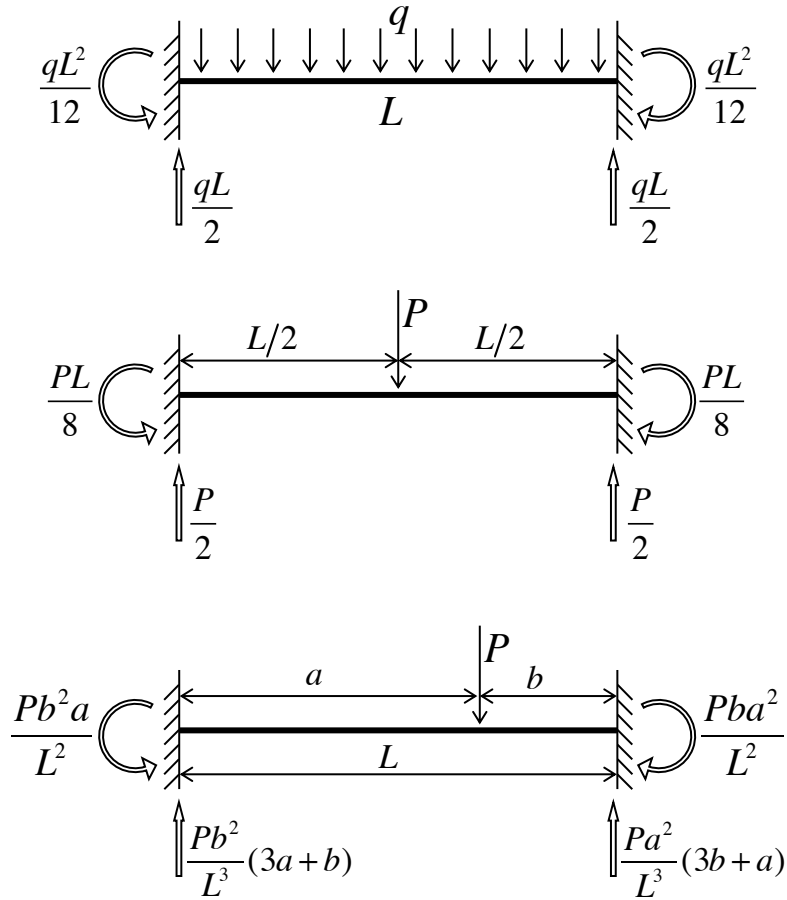
External forces applied to structure: $\mathbf{Ku} = \mathbf{F}$

Split member forces and point loads: $\mathbf{Ku} + \bar{\mathbf{F}} = \hat{\mathbf{F}}$

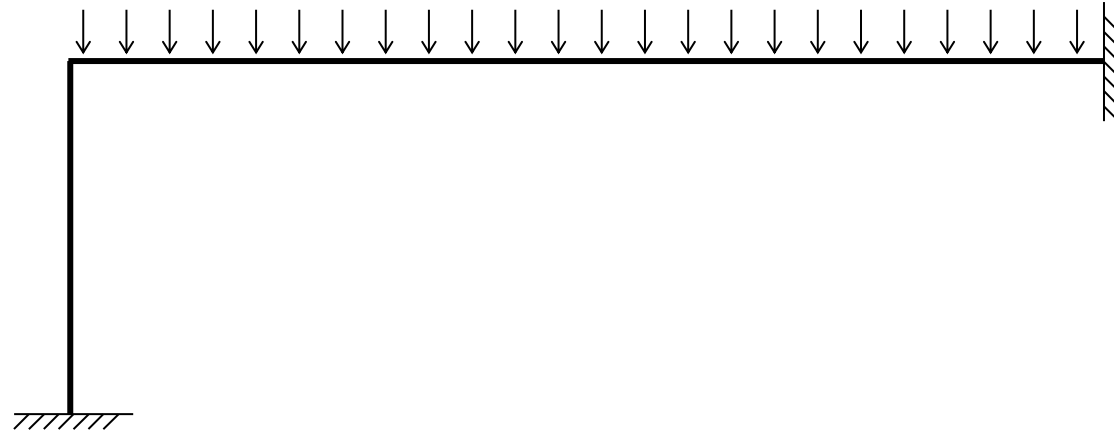
Total load vector: $\mathbf{Ku} = \hat{\mathbf{F}} - \bar{\mathbf{F}} = \mathbf{F}$

Member end forces after solving equilibrium equations: $\mathbf{F} = \mathbf{Ku} + \bar{\mathbf{F}}$

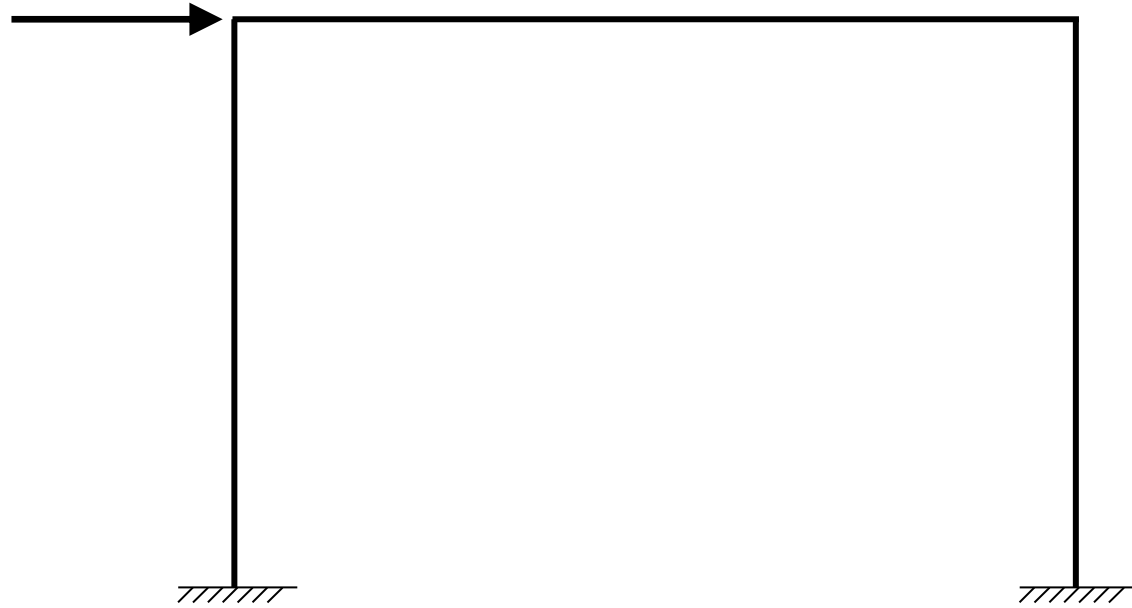
Formula Sheet for \bar{F}



Example



Example



More lectures:

Terje's Toolbox:

terje.civil.ubc.ca